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Reviews of Nonlinear Dynamics and Complexity Heinz Georg Schuster, 2009-09-03 Adopting a cross disciplinary approach the review character of this monograph sets it apart from specialized journals The editor is advised by a first class board of international scientists such that the carefully selected and invited contributions represent the latest and most relevant findings The resulting review enables both researchers and newcomers in life science physics and chemistry to access the most important results in this field using a common language

Computational Methods in Applied Mathematics, 2005 *Identification of Nonlinear Systems Using Neural Networks and Polynomial Models* Andrzej Janczak, 2004-11-18 This monograph systematically presents the existing identification methods of nonlinear systems using the block oriented approach It surveys various known approaches to the identification of Wiener and Hammerstein systems which are applicable to both neural network and polynomial models The book gives a comparative study of their gradient approximation accuracy computational complexity and convergence rates and furthermore presents some new and original methods concerning the model parameter adjusting with gradient based techniques Identification of Nonlinear Systems Using Neural Networks and Polynomial Models is useful for researchers engineers and graduate students in nonlinear systems and neural network theory

Discrete and Continuous Dynamical Systems, 2008 *Mathematical Reviews*, 2003 **American Book Publishing Record**, 2002 **Theory of the Non-linear Analog Phase Locked Loop** Nikolaos I. Margaris, 2004-05-18 This book develops for the first time a complete and connected nonlinear theory for the analog Phase Locked Loop PLL which clarifies the obscure points of its complex non linear behaviour The book suggests new non linear models for the PLL components and applies the averaging method to analyse PLL The book presents the physical interpretation of the PLL operation locates the difficulties presented by its operation and suggests solutions to overcome these problems Finally it provides closed form expressions for all the important measures of the PLL and proposes new design criteria

Theory of Vibro-Impact Systems and Applications Vladimir I. Babitsky, 2013-11-11 Models of vibro impact systems are widely used in machine dynamics vibration engineering and structural mechanics Only monograph on this subject in English language Systematically presents the theory of vibro impact systems by analysis of typical engineering applications Experimental data and computer simulations are presented Targeted to engineers and researchers in design and investigation of mechanical systems as well as to lecturers and advanced students

Cooperative Behavior in Neural Systems Pedro L. Garrido, Joaquín Marro, Joaquín J. Torres, 2007-02-23 This volume features peer reviewed papers from the 9th Granada Seminar which was held at the Facultad de Ciencias of the University of Granada Spain September 11 15 2006 The 9th Granada Seminar covered the computational and mathematical modeling of cooperative behavior in neural systems and provided young scientists the opportunity to present their results and to discuss their problems with leading specialists

Advances in Rehabilitation Robotics Z. Zenn Bien, Dimitar Stefanov, 2004-06-24 One of the major application targets

of service robots is to use them as assistive devices for rehabilitation This book introduces some latest achievements in the field of rehabilitation robotics and assistive technology for people with disabilities and aged people The book contains results from both theoretical and experimental works and reviews on some new advanced rehabilitation devices which has been recently transferred to the industry Significant parts of the book are devoted to the assessment of new rehabilitation technologies the evaluation of prototype devices with end users the safety of rehabilitation robots and robot assisted neurorehabilitation The book is a representative selection of the latest trends in rehabilitation robotics and can be used as a reference for teaching on mechatronic devices for rehabilitation

Experimental Robotics M. Ani Hsieh, Oussama Khatib, Vijay Kumar, 2015-11-21 The International Symposium on Experimental Robotics ISER is a series of bi annual meetings which are organized in a rotating fashion around North America Europe and Asia Oceania The goal of ISER is to provide a forum for research in robotics that focuses on novelty of theoretical contributions validated by experimental results The meetings are conceived to bring together in a small group setting researchers from around the world who are in the forefront of experimental robotics research This unique reference presents the latest advances across the various fields of robotics with ideas that are not only conceived conceptually but also explored experimentally It collects robotics contributions on the current developments and new directions in the field of experimental robotics which are based on the papers presented at the 14th ISER held on June 15 18 2014 in Marrakech and Essaouira Morocco This present fourteenth edition of Experimental Robotics edited by M Ani Hsieh Oussama Khatib and Vijay Kumar offers a collection of a broad range of topics in field and human centered robotics

Advanced Models of Neural Networks Gerasimos G. Rigatos, 2014-08-27 This book provides a complete study on neural structures exhibiting nonlinear and stochastic dynamics elaborating on neural dynamics by introducing advanced models of neural networks It overviews the main findings in the modelling of neural dynamics in terms of electrical circuits and examines their stability properties with the use of dynamical systems theory It is suitable for researchers and postgraduate students engaged with neural networks and dynamical systems theory

Control Applications of Optimisation 2003 (CAO 2003) R. Bars, É Gyurkovics, 2003 A Proceedings volume from the IFAC Workshop on Control Applications of Optimisation Visegrad June July 2003 Presents the findings of experts and practitioners in the field provides an overview of the theory and applications and documentation of the scientific activities of the workshop

Probabilistic Methods in Applied Physics Paul Kree, 1995-10-09 This book is an outcome of a European collaboration on applications of stochastic methods to problems of science and engineering The articles present methods allowing concrete calculations without neglecting the mathematical foundations They address physicists and engineers interested in scientific computation and simulation techniques In particular the volume covers simulation stability theory Lyapounov exponents stochastic modelling statistics on trajectories parametric stochastic control Fokker Planck equations and Wiener filtering

Nonlinear Control Systems Design 1992 Michel Fliess, 1993 Hardbound This volume represents most aspects of

the rich and growing field of nonlinear control These proceedings contain 78 papers including six plenary lectures striking a balance between theory and applications Subjects covered include feedback stabilization nonlinear and adaptive control of electromechanical systems nonholonomic systems Generalized state space systems algebraic computing in nonlinear systems theory decoupling linearization and model matching and robust control are also covered *Singular Perturbations in Systems and Control* Kokotovic Petar V, Michael A. Soderstrand, Hassan K. Khalil, IEEE Control Systems Society, 1986 Very Good No Highlights or Markup all pages are intact Dynamics, Bifurcations and Control Fritz Colonius, Lars Grüne, 2002-01-11 This volume originates from the Third Nonlinear Control Workshop Dynamics Bifurcations and Control held in Kloster Irsee April 13 2001 As the preceding workshops held in Paris 2000 and in Ghent 1999 it was organized within the framework of Nonlinear Control Network funded by the European Union <http://www.supelec.fr/lss/NCN> The papers in this volume center around those control problems where phenomena and methods from dynamical systems theory play a dominant role Despite the large variety of techniques and methods present in the contributions a rough subdivision can be given into three areas Bifurcation problems stabilization and robustness and global dynamics of control systems A large part of the fascination in nonlinear control stems from the fact that it is deeply rooted in engineering and mathematics alike The contributions to this volume reflect this double nature of nonlinear control We would like to take this opportunity to thank all the contributors and the referees for their careful work Furthermore it is our pleasure to thank Franchise Lamnabhi Lagarrigue the coordinator of our network for her support in organizing the workshop and the proceedings and for the tremendous efforts she puts into this network bringing the cooperation between the different groups to a new level In particular the exchange and the active participation of young scientists also reflected in the Pedagogical Schools within the Network is an asset for the field of nonlinear control *Scientific and Technical Books and Serials in Print* ,1989 Books in Print ,1987 *Physics Briefs* ,1979

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