Thomas Steffen

Control Reconfiguration of Dynamical Systems

Control Reconfiguration Of Dynamical Systems Linear Approaches And Structural Tests Lecture Notes

Mogens Blanke,Michel Kinnaert,Jan Lunze,Marcel Staroswiecki

Control Reconfiguration Of Dynamical Systems Linear Approaches And Structural Tests Lecture Notes:

Control Reconfiguration of Dynamical Systems Thomas Steffen,2005-08-31 Reconfiguration an approach for fault tolerant control involves changing the control structure in response to the fault This monograph extends this idea to actuator faults and studies in detail the so called virtual actuator approach Control Reconfiguration of Dynamical Systems also introduces structural analysis as a tool for reconfiguration Because a fault changes the structure of the system the reconfiguration solution is sought on a structural level Novel algorithms are presented to test for reconfigurability and to find a reconfiguration solution A MATLAB toolbox is supplied which contains the main algorithms and examples The book addresses advanced engineering students developers and researchers that have a specific interest in control reconfiguration

Advances in Gain-Scheduling and Fault Tolerant Control Techniques Damiano Rotondo,2017-10-14 This thesis reports on novel methods for gain scheduling and fault tolerant control FTC It begins by analyzing the connection between the linear parameter varying LPV and Takagi Sugeno TS paradigms This is then followed by a detailed description of the design of robust and shifting state feedback controllers for these systems Furthermore it presents two approaches to fault tolerant control the first is based on a robust polytopic controller design while the second involves a reconfiguration of the reference model and the addition of virtual actuators into the loop Inaddition the thesis offers a thorough review of the state of the art in gain scheduling and fault tolerant control with a special emphasis on LPV and TS systems **Fault Diagnosis and Fault-Tolerant Control and Guidance for Aerospace Vehicles** Ali Zolghadri,David Henry,Jérôme Cieslak,Denis Efimov,Philippe Goupil,2013-10-07 Fault Diagnosis and Fault Tolerant Control and Guidance for Aerospace demonstrates the attractive potential of recent developments in control for resolving such issues as flight performance self protection and extended life structures Importantly the text deals with a number of practically significant considerations tuning complexity of design real time capability evaluation of worst case performance robustness in harsh environments and extensibility when development or adaptation is required Coverage of such issues helps to draw the advanced concepts arising from academic research back towards the technological concerns of industry Initial coverage of basic definitions and ideas and a literature review gives way to a treatment of electrical flight control system failures oscillatory failure runaway and jamming Advanced fault detection and diagnosis for linear and linear parameter varying systems are described Lastly recovery strategies appropriate to remaining actuator sensor communications resources are developed The authors exploit experience gained in research collaboration with academic and major industrial partners to validate advanced fault diagnosis and fault tolerant control techniques with realistic benchmarks or real world aeronautical and space systems Consequently the results presented in Fault Diagnosis and Fault Tolerant Control and Guidance for Aerospace will be of interest in both academic and aerospatial industrial milieux **Service Orientation in Holonic and Multi-agent Manufacturing** Theodor Borangiu,André Thomas,Damien Trentesaux,2015-02-17 This volume gathers the peer reviewed papers presented at the 4th

edition of the International Workshop Service Orientation in Holonic and Multi agent Manufacturing SOHOMA 14 organized and hosted on November 5 6 2014 by the University of Lorraine France in collaboration with the CIMR Research Centre of the University Politehnica of Bucharest and the TEMPO Laboratory of the University of Valenciennes and Hainaut Cambr sis The book is structured in six parts each one covering a specific research line which represents a trend in future manufacturing 1 Holonic and Agent based Industrial Automation Systems 2 Service oriented Management and Control of Manufacturing Systems 3 Distributed Modelling for Safety and Security in Industrial Systems 4 Complexity Big Data and Virtualization in Computing oriented Manufacturing 5 Adaptive Bio inspired and Self organizing Multi Agent Systems for Manufacturing and 6 Physical Internet Simulation Modelling and Control There is a clear orientation of the SOHOMA 14 workshop towards complexity which is a common view of all six parts There is need for a framework allowing the development of manufacturing cyber physical systems including capabilities for complex event processing and data analytics which are expected to move the manufacturing domain closer towards cloud manufacturing within contextual enterprises Recent advances in sensor communication and intelligent computing technologies made possible the Internet connectivity of the physical world the Physical Internet where not only documents and images are created shared or modified in the cyberspace but also the physical resources and products interact over Internet and make decisions based on shared communication   Mathematical Reviews ,2006   **Deutsche Nationalbibliografie** ,2005-07   **Reconfigurable Control of Nonlinear Dynamical Systems** Jan H. Richter,2011-02-02 This research monograph summarizes solutions to reconfigurable fault tolerant control problems for nonlinear dynamical systems that are based on the fault hiding principle It emphasizes but is not limited to complete actuator and sensor failures In the first part the monograph starts with a broad introduction of the control reconfiguration problems and objectives as well as summaries and explanations of solutions for linear dynamical systems The solution is always a reconfiguration block which consists of linear virtual actuators in the case of actuator faults and linear virtual sensors in the case of sensor faults The main advantage of the fault hiding concept is the reusability of the nominal controller which remains in the loop as an active system while the virtual actuator and sensor adapt the control input and the measured output to the fault scenario The second and third parts extend virtual actuators and virtual sensors towards the classes of Hammerstein Wiener systems and piecewise affine systems The main analyses concern stability recovery setpoint tracking recovery and performance recovery as reconfiguration objectives The fourth part concludes the monograph with descriptions of practical implementations and case studies The book is primarily intended for active researchers and practicing engineers in the field of fault tolerant control Due to many running examples it is also suitable for interested graduate students   **Thirty-sixth AIAA/ASME/ASCE/AHS/ASC Structures, Structural Dynamics, and Materials Conference and AIAA/ASME Adaptive Structures Forum** ,1995   Commerce Business Daily ,1997-12-31   *Diagnosis and Fault-Tolerant Control* Mogens Blanke,Michel Kinnaert,Jan Lunze,Marcel

Staroswiecki,2015-08-11 Fault tolerant control aims at a gradual shutdown response in automated systems when faults occur It satisfies the industrial demand for enhanced availability and safety in contrast to traditional reactions to faults which bring about sudden shutdowns and loss of availability The book presents effective model based analysis and design methods for fault diagnosis and fault tolerant control Architectural and structural models are used to analyse the propagation of the fault through the process to test the fault detectability and to find the redundancies in the process that can be used to ensure fault tolerance It also introduces design methods suitable for diagnostic systems and fault tolerant controllers for continuous processes that are described by analytical models of discrete event systems represented by automata The book is suitable for engineering students engineers in industry and researchers who wish to get an overview of the variety of approaches to process diagnosis and fault tolerant control The authors have extensive teaching experience with graduate and PhD students as well as with industrial experts Parts of this book have been used in courses for this audience The authors give a comprehensive introduction to the main ideas of diagnosis and fault tolerant control and present some of their most recent research achievements obtained together with their research groups in a close cooperation with European research projects The third edition resulted from a major re structuring and re writing of the former edition which has been used for a decade by numerous research groups New material includes distributed diagnosis of continuous and discrete event systems methods for reconfigurability analysis and extensions of the structural methods towards fault tolerant control The bibliographical notes at the end of all chapters have been up dated The chapters end with exercises to be used in lectures   Structural Methods in the Study of Complex Systems Elena Zattoni,Anna Maria Perdon,Giuseppe Conte,2019-06-27 Structural Methods in the Study of Complex Systems helps the reader respond to the challenge of mastering complexity in systems and control The book details the fundamental control problems arising from complex dynamical systems and shows how they can be tackled effectively by means of methods developed from graph theory differential algebra and geometric approaches These structural methods produce abstractions that fit a wide variety of applications by taking advantage of their intrinsic focus on the essential characteristics of dynamical systems their geometric perspective and visual representation and their algebraic formalization and ability to generate algorithmic frameworks to complement the theoretical treatment The original work and latest achievements of the contributors expanding on material presented at a workshop organized to coincide with the 2018 European Control Conference will assist systems and control scientists interested in developing theoretical and computational tools to solve analysis and synthesis problems involving complex dynamical systems The contributions provide a comprehensive picture of available results along with a stimulating view of possible directions for future investigations in the field Emphasis is placed on methods with solid computational background and on specific engineering applications so that readers from both theoretical and practical backgrounds will find this collection of use   Diagnosis and Fault-Tolerant Control Mogens Blanke,Michel Kinnaert,Jan Lunze,Marcel Staroswiecki,2006-09-24 Fault tolerant control aims at a graceful

degradation of the behaviour of automated systems in case of faults It satisfies the industrial demand for enhanced availability and safety in contrast to traditional reactions to faults that bring about sudden shutdowns and loss of availability The book presents effective model based analysis and design methods for fault diagnosis and fault tolerant control Architectural and structural models are used to analyse the propagation of the fault throught the process to test the fault detectability and to find the redundancies in the process that can be used to ensure fault tolerance Design methods for diagnostic systems and fault tolerant controllers are presented for processes that are described by analytical models by discrete event models or that can be dealt with as quantised systems Five case studies on pilot processes show the applicability of the presented methods The theoretical results are illustrated by two running examples used throughout the book The second edition includes new material about reconfigurable control diagnosis of nonlinear systems and remote diagnosis The application examples are extended by a steering by wire system and the air path of a diesel engine both of which include experimental results The bibliographical notes at the end of all chapters have been up dated The chapters end with exercises to be used in lectures **Linear Dynamical Systems** Mircea D. Grigoriu,2021-01-30 This textbook provides a concise clear and rigorous presentation of the dynamics of linear systems that delivers the necessary tools for the analysis and design of mechanical structural systems regardless of their complexity The book is written for senior undergraduate and first year graduate students as well as engineers working on the design of mechanical structural systems subjected to dynamic actions such as wind earthquake engineers and mechanical engineers working on wind turbines Professor Grigoriu s lucid presentation maximizes student understanding of the formulation and the solution of linear systems subjected to dynamic actions and provides a clear distinction between problems of practical interest and their special cases Based on the author s lecture notes from courses taught at Cornell University the material is class tested over many years and ideal as a core text for a range of classes in mechanical civil and geotechnical engineering as well as for self directed learning by practitioners in the field **Robust Control of Uncertain Dynamic Systems** Rama K. Yedavalli,2013-12-06 This textbook aims to provide a clear understanding of the various tools of analysis and design for robust stability and performance of uncertain dynamic systems In model based control design and analysis mathematical models can never completely represent the real world system that is being modeled and thus it is imperative to incorporate and accommodate a level of uncertainty into the models This book directly addresses these issues from a deterministic uncertainty viewpoint and focuses on the interval parameter characterization of uncertain systems Various tools of analysis and design are presented in a consolidated manner This volume fills a current gap in published works by explicitly addressing the subject of control of dynamic systems from linear state space framework namely using a time domain matrix theory based approach This book also Presents and formulates the robustness problem in a linear state space model framework Illustrates various systems level methodologies with examples and applications drawn from aerospace electrical and mechanical engineering Provides connections between

lyapunov based matrix approach and the transfer function based polynomial approaches Robust Control of Uncertain Dynamic Systems A Linear State Space Approach is an ideal book for first year graduate students taking a course in robust control in aerospace mechanical or electrical engineering   *Lectures On Dynamical Systems, Structural Stability And Their Applications* Kotik K Lee,1992-05-14 The communication of knowledge on nonlinear dynamical systems between the mathematicians working on the analytic approach and the scientists working mostly on the applications and numerical simulations has been less than ideal This volume hopes to bridge the gap between books written on the subject by mathematicians and those written by scientists The second objective of this volume is to draw attention to the need for cross fertilization of knowledge between the physical and biological scientists The third aim is to provide the reader with a personal guide on the study of global nonlinear dynamical systems   *Structural Stability of Dynamical Systems* Norman Schofield,1972   *Robust Control of Linear Systems Subject to Uncertain Time-Varying Parameters* Francesco Amato,2006-02-21 The last thirty years have witnessed an enormous effort in the field of robust control of dynamical systems The main objective of this book is that of presenting in a unified framework the main results appeared in the literature on this topic with particular reference to the robust stability problem for linear systems subject to time varying uncertainties The book mainly focuses on those problems for which a definitive solution has been found indeed most of the results we shall present are given in the form of necessary and sufficient conditions involving the feasibility of Linear Matrix Inequalities based problems For self containedness purposes most of the results provided in the book are proven We have tried to maintain the development of the proofs as simple as possible without sacrificing the mathematical rigor Some parts of the book especially those contained in Chaps 2 3 and 5 can be teached in advanced control courses however this work is mainly devoted to both researchers in the field of systems and control theory and engineers working in industries which want to apply the methodologies presented in the book to practical control problems To this regard as the various results are derived they are immediately reinforced with real world examples   *Stability and Control of Dynamical Systems with Applications* Derong Liu,Panos J. Antsaklis,2003-06-24 It is with great pleasure that I offer my reflections on Professor Anthony N Michel s retirement from the University of Notre Dame I have known Tony since 1984 when he joined the University of Notre Dame s faculty as Chair of the Depart ment of Electrical Engineering Tony has had a long and outstanding career As a researcher he has made im portant contributions in several areas of systems theory and control theory espe cially stability analysis of large scale dynamical systems The numerous awards he received from the professional societies particularly the Institute of Electrical and Electronics Engineers IEEE are a testament to his accomplishments in research He received the IEEE Control Systems Society s Best Transactions Paper Award 1978 and the IEEE Circuits and Systems Society s Guillemin Cauer Prize Paper Award 1984 and Myril B Reed Outstanding Paper Award 1993 among others In addition he was a Fulbright Scholar 1992 and received the Alexander von Hum boldt Forschungspreis Alexander von Humboldt Research Award for Senior U S

Scientists from the German government 1997 To date he has written eight books and published over 150 archival journal papers Tony is also an effective administrator who inspires high academic standards   **Linear Systems Theory** Ben M. Chen,Zongli Lin,Yacov Shamash,2004-08-27 Includes MATLAB based computational and design algorithms utilizing the Linear Systems Toolkit All results and case studies presented in both the continuous and discrete time settings   **Theoretical and Computational Aspects of Structural Dynamical Systems in Linear Algebra and Control** Luciano Lopez,2003

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