

Rama K. Yedavalli

Robust Control of Uncertain Dynamic Systems

A Linear State Space Approach

Control Of Uncertain Dynamic Systems

Christopher Ian Marrison



Control Of Uncertain Dynamic Systems:

Robust Control of Uncertain Dynamic Systems Rama K. Yedavalli, 2013-12-05 This textbook aims to provide a clear understanding of the various tools of analysis and design for robust stability and performance of uncertain dynamic systems. In model based control design and analysis mathematical models can never completely represent the real world system that is being modeled and thus it is imperative to incorporate and accommodate a level of uncertainty into the models. This book directly addresses these issues from a deterministic uncertainty viewpoint and focuses on the interval parameter characterization of uncertain systems. Various tools of analysis and design are presented in a consolidated manner. This volume fills a current gap in published works by explicitly addressing the subject of control of dynamic systems from linear state space framework namely using a time domain matrix theory based approach. This book also presents and formulates the robustness problem in a linear state space model framework. Illustrates various systems level methodologies with examples and applications drawn from aerospace electrical and mechanical engineering. Provides connections between Lyapunov based matrix approach and the transfer function based polynomial approaches. **Robust Control of Uncertain Dynamic Systems: A Linear State Space Approach** is an ideal book for first year graduate students taking a course in robust control in aerospace mechanical or electrical engineering.

Control of Uncertain Dynamic Systems Shankar P. Bhattacharyya, Lee H. Keel, 2020-09-23 This book is a collection of 34 papers presented by leading researchers at the International Workshop on Robust Control held in San Antonio Texas in March 1991. The common theme tying these papers together is the analysis, synthesis and design of control systems subject to various uncertainties. The papers describe the latest results in parametric uncertainty, H_∞ control and Quantitative Feedback Theory (QFT). The book is the first to bring together all the diverse points of view addressing the robust control problem and should strongly influence development in the robust control field for years to come. For this reason control theorists, engineers and applied mathematicians should consider it a crucial acquisition for their libraries.

Control of Uncertain Dynamic Systems S. P. Bhattacharyya, L. H. Keel, 1991
Estimators for Uncertain Dynamic Systems A.I. Matasov, 2012-12-06 When solving the control and design problems in aerospace and naval engineering, energetics, economics, biology etc we need to know the state of investigated dynamic processes. The presence of inherent uncertainties in the description of these processes and of noises in measurement devices leads to the necessity to construct the estimators for corresponding dynamic systems. The estimators recover the required information about system state from measurement data. An attempt to solve the estimation problems in an optimal way results in the formulation of different variational problems. The type and complexity of these variational problems depend on the process model, the model of uncertainties and the estimation performance criterion. A solution of variational problem determines an optimal estimator. However, there exist at least two reasons why we use nonoptimal estimators. The first reason is that the numerical algorithms for solving the corresponding variational problems can be very

difficult for numerical implementation For example the dimension of these algorithms can be very high

Structural Dynamic Systems Computational Techniques and Optimization Cornelius T. Leondes, 1999 Conventional seismic design has been based on structural strength in the initial design of structures resulting in lateral force resisting systems with sufficient strength to be able to absorb and dissipate the seismic For important structures such as urban high speed road systems high rise buildings hospitals airports and other essential structures which must be quite functional after an earthquake modern seismic structural design techniques have been developed with a view toward eliminating or significantly reducing seismic damage to such structures This volume is a comprehensive treatment of the issues involved in modern seismic design techniques for structure with a view to significantly enhancing their capability of surviving earthquakes to an adequate degree i e enhancing the ability of structural systems to withstand high level earthquakes

Resilient Control of Uncertain Dynamical Systems Magdi S. Mahmoud, 2004-05-18 This monograph provides a complete description of resilient control theory It unifies the methods for developing resilient controllers and filters for a class of uncertain dynamical systems and reports recent advances in design methodologies The book presents an introductory and comprehensive treatment of resilient controller design methods placing great emphasis on the derivation of necessary and sufficient design conditions and on the use of linear matrix inequalities as a convenient computational tool The book can be used as a graduate level textbook in control engineering or applied mathematics as well as a reference for practicing engineers researchers and students

Control and Dynamic Systems V50: Robust Control System Techniques and Applications C.T. Leonides, 2012-12-02 Control and Dynamic Systems Advances in Theory and Applications Volume 50 Robust Control System Techniques and Applications Part 1 of 2 is a two volume sequence devoted to the issues and application of robust control systems techniques This volume is composed of 10 chapters and begins with a presentation of the important techniques for dealing with conflicting design objectives in control systems The subsequent chapters describe the robustness techniques of systems using differential difference equations the design of a wide class of robust nonlinear systems the techniques for dealing with the problems resulting from the use of observers in robust systems design and the effective techniques for the robust control on non linear time varying of tracking control systems with uncertainties These topics are followed by discussions of the effective techniques for the robust control on non linear time varying of tracking control systems with uncertainties and for incorporating adaptive control techniques into a non adaptive robust control design Other chapters present techniques for achieving exponential and robust stability for a rather general class of nonlinear systems techniques in modeling uncertain dynamics for robust control systems design and techniques for the optimal synthesis of these systems The last chapters provide a generalized eigenproblem solution for both singular and nonsingular system cases These chapters also look into the stability robustness design for discrete time systems This book will be of value to process and systems engineers designers and researchers

Adaptive Control of Dynamic Systems with Uncertainty and Quantization

Jing Zhou, Lantao Xing, Changyun Wen, 2021-12-14 This book presents a series of innovative technologies and research results on adaptive control of dynamic systems with quantization uncertainty and nonlinearity including the theoretical success and practical development such as the approaches for stability analysis the compensation of quantization the treatment of subsystem interactions and the improvement of system tracking and transient performance Novel solutions by adopting backstepping design tools to a number of hotspots and challenging problems in the area of adaptive control are provided In the first three chapters the general design procedures and stability analysis of backstepping controllers and the basic descriptions and properties of quantizers are introduced as preliminary knowledge for this book In the remainder of this book adaptive control schemes are introduced to compensate for the effects of input quantization state quantization both input and state output quantization for uncertain nonlinear systems and are applied to helicopter systems and DC Microgrid Discussion remarks are provided in each chapter highlighting new approaches and contributions to emphasize the novelty of the presented design and analysis methods Simulation results are also given in each chapter to show the effectiveness of these methods This book is helpful to learn and understand the fundamental backstepping schemes for state feedback control and output feedback control It can be used as a reference book or a textbook on adaptive quantized control for students with some background in feedback control systems Researchers graduate students and engineers in the fields of control information and communication electrical engineering mechanical engineering computer science and others will benefit from this book

Journal of Dynamic Systems, Measurement, and Control, 2001 Publishes theoretical and applied original papers in dynamic systems Theoretical papers present new theoretical developments and knowledge for controls of dynamical systems together with clear engineering motivation for the new theory Applied papers include modeling simulation and corroboration of theory with emphasis on demonstrated practicality

Robust Control Design for Uncertain Dynamic Systems Ye-Hwa Chen, Georgia Institute of Technology. Mechanical Engineering. Project E-25-678, 1990

Robust Control Design for Uncertain Nonlinear Dynamic Systems Myung-Chul Han, 1992

State Estimation for Dynamic Systems Felix L. Chernousko, 1993-11-09 State Estimation for Dynamic Systems presents the state of the art in this field and discusses a new method of state estimation The method makes it possible to obtain optimal two sided ellipsoidal bounds for reachable sets of linear and nonlinear control systems with discrete and continuous time The practical stability of dynamic systems subjected to disturbances can be analyzed and two sided estimates in optimal control and differential games can be obtained The method described in the book also permits guaranteed state estimation filtering for dynamic systems in the presence of external disturbances and observation errors Numerical algorithms for state estimation and optimal control as well as a number of applications and examples are presented The book will be an excellent reference for researchers and engineers working in applied mathematics control theory and system analysis It will also appeal to pure and applied mathematicians control engineers and computer programmers

Advanced Control of Chemical Processes 1997 (ADCHEM'97) Sirish L.

Shah,Y. Arkun,1997 Paperback Advanced Control of Chemical Processes 1997 was an international event It attracted a total of 205 participants from industry and academia around the world Over 100 papers were presented at this symposium including 3 plenary addresses and 6 keynote talks The main themes included process monitoring pulp and paper process control model predictive control and modelling and simulation

Robust Control of Nonlinear Uncertain Systems

Zhihua Qu,1998-04-29 This timely work presents the definitive treatment of stability analysis and robust control design for nonlinear uncertain systems While other books on the subject deal with robust control in linear systems this is the first book to tackle robust control design for such nonlinear entities as power systems robotics and more It combines examples proofs and applications clearly showing how to build high performance and better control into systems that are too complex to be modeled accurately A unique feature of this book is its Lyapunov based approach to control design which is the only universal approach for nonlinear systems The Lyapunov direct method is used here to develop all design procedures to correlate leading techniques in the field to the structural properties of uncertain systems and to compare robust and nonrobust types of controls such as adaptive control learning control and optimal control The subject is introduced with a self contained treatment of the nonlinear stability theory originally proposed by Lyapunov and LaSalle Emphasizing the basics the introductory chapters incorporate three types of solutions stability concepts and various theorems The main body of the text offers a comprehensive treatment for current design methods including state space robust control designs properties of various robust controllers input output control and discrete robust control designs In Robust Control of Nonlinear Uncertain Systems author Zhihua Qu presents the complete set of control design procedures for nonlinear uncertain systems including backward recursive design forward recursive design recursive interlacing design feedback linearization nonlinear optimal control and sub optimal control Also featured here is the breakthrough recursive interlacing design that facilitates robust control for uncertain systems with all cascaded feedback and feedforward dynamics Throughout Professor Qu presents the pros and cons of specific methods rationales for choosing particular design parameters and tips on questions of stability performance and systems structure For engineers and graduate students in mechanical electrical and aerospace engineering Robust Control of Nonlinear Uncertain Systems imparts the technical know how for effective design explores key theoretical issues in control and provides insight into future trends in the field

Performance-Driven Robust Identification and Control of Uncertain Dynamical Systems,2001

The grant DEFG02 97ER13939 from the Department of Energy has supported our research program on robust identification and control of uncertain dynamical systems initially for the three year period June 15 1997 June 14 2000 which was then extended on a no cost basis for another year until June 14 2001 This final report provides an overview of our research conducted during this period along with a complete list of publications supported by the Grant Within the scope of this project we have studied fundamental issues that arise in modeling identification filtering control stabilization control based model reduction decomposition and aggregation and optimization of uncertain systems

The mathematical framework we have worked in has allowed the system dynamics to be only partially known with the uncertainties being of both parametric or structural nature and further the dynamics to be perturbed by unknown dynamic disturbances. Our research over these four years has generated a substantial body of new knowledge and has led to new major developments in theory applications and computational algorithms. These have all been documented in various journal articles and book chapters and have been presented at leading conferences as to be described. A brief description of the results we have obtained within the scope of this project can be found in Section 3. To set the stage for the material of that section we first provide in the next section Section 2 a brief description of the issues that arise in the control of uncertain systems and introduce several criteria under which optimality will lead to robustness and stability. Section 4 contains a list of references cited in these two sections. A list of our publications supported by the DOE Grant covering the period June 15 1997 June 14 2001 comprises Section 5 of the report.

Robust Discrete Time Control of Uncertain Continuous Time Plants Alireza Jabbari, 1992

The Design of Control Laws for Uncertain Dynamic Systems Using Stochastic Robustness Metrics Christopher Ian Marrison, 1995

Robust Control of Uncertain Nonlinear Dynamical Systems Ahmad Abdalla, 1994

Soft Numerical Computing in Uncertain Dynamic Systems Tofiq Allahviranloo, Witold Pedrycz, 2020-08-19

Soft Numerical Computing in Uncertain Dynamic Systems is intended for system specialists interested in dynamic systems that operate at different time scales. The book discusses several types of errors and their propagation covering numerical methods including convergence and consistence properties and characteristics and proving of related theorems within the setting of soft computing. Several types of uncertainty representation like interval fuzzy type 2 fuzzy granular and combined uncertain sets are discussed in detail. The book can be used by engineering students in control and finite element fields as well as all engineering applied mathematics economics and computer science students. One of the important topics in applied science is dynamic systems and their applications. The authors develop these models and deliver solutions with the aid of numerical methods. Since they are inherently uncertain soft computations are of high relevance here. This is the reason behind investigating soft numerical computing in dynamic systems. If these systems are involved with complex uncertain data they will be more practical and important. Real life problems work with this type of data and most of them cannot be solved exactly and easily sometimes they are impossible to solve. Clearly all the numerical methods need to consider error of approximation. Other important applied topics involving uncertain dynamic systems include image processing and pattern recognition which can benefit from uncertain dynamic systems as well. In fact the main objective is to determine the coefficients of a matrix that acts as the frame in the image. One of the effective methods exhibiting high accuracy is to use finite differences to fill the cells of the matrix. Explores dynamic models how time is fundamental to the structure of the model and data and how a process unfolds. Investigates the dynamic relationships between multiple components of a system in modeling using mathematical models and the concept of stability in uncertain environments. Exposes readers to many soft numerical methods.

to simulate the solution function s behavior

Uncertain Dynamical Systems A.A. Martynyuk, Yu. A.

Martynyuk-Chernienko, 2011-11-28 This self contained book provides systematic instructive analysis of uncertain systems of the following types ordinary differential equations impulsive equations equations on time scales singularly perturbed differential equations and set differential equations Each chapter contains new conditions of stability of unperturbed motion of the above mentioned type of equations along with some applications Without assuming specific knowledge of uncertain dynamical systems the book includes many fundamental facts about dynamical behaviour of its solutions Giving a concise review of current research developments Uncertain Dynamical Systems Stability and Motion Control Details all proofs of stability conditions for five classes of uncertain systems Clearly defines all used notions of stability and control theory Contains an extensive bibliography facilitating quick access to specific subject areas in each chapter Requiring only a fundamental knowledge of general theory of differential equations and calculus this book serves as an excellent text for pure and applied mathematicians applied physicists industrial engineers operations researchers and upper level undergraduate and graduate students studying ordinary differential equations impulse equations dynamic equations on time scales and set differential equations

The Enigmatic Realm of **Control Of Uncertain Dynamic Systems**: Unleashing the Language is Inner Magic

In a fast-paced digital era where connections and knowledge intertwine, the enigmatic realm of language reveals its inherent magic. Its capacity to stir emotions, ignite contemplation, and catalyze profound transformations is nothing short of extraordinary. Within the captivating pages of **Control Of Uncertain Dynamic Systems** a literary masterpiece penned with a renowned author, readers set about a transformative journey, unlocking the secrets and untapped potential embedded within each word. In this evaluation, we shall explore the book's core themes, assess its distinct writing style, and delve into its lasting effect on the hearts and minds of those who partake in its reading experience.

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