Discrete time system

Discrete time system

$$y(n) = -b_1 y(n-1) + a_0 x(n)$$
 (6-1)

where a_0 and b_1 are multiplier

D is delay element

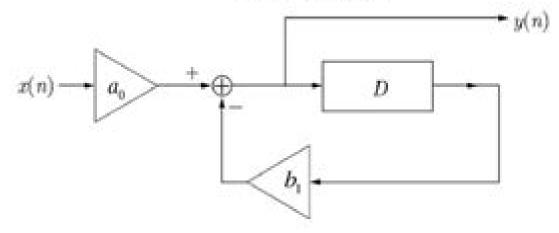


Fig. 6-1.

Discrete Time And Computer Control Systems

Huibert Kwakernaak, Raphel Sivan

Discrete Time And Computer Control Systems:

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Computer Control Systems Technology Cornelius T. Leondes, 1961

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Sivan,1972-11-10 This book attempts to reconcile modern linear control theory with classical control theory One of the major concerns of this text is to present design methods employing modern techniques for obtaining control systems that stand up to the requirements that have been so well developed in the classical expositions of control theory Therefore among other things an entire chapter is devoted to a description of the analysis of control systems mostly following the classical lines of thought In the later chapters of the book in which modern synthesis methods are developed the chapter on analysis is recurrently referred to Furthermore special attention is paid to subjects that are standard in classical control theory but are frequently overlooked in modern treatments such as nonzero set point control systems tracking systems and control systems that have to cope with constant disturbances Also heavy emphasis is placed upon the stochastic nature of control problems because the stochastic aspects are so essential Preface

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