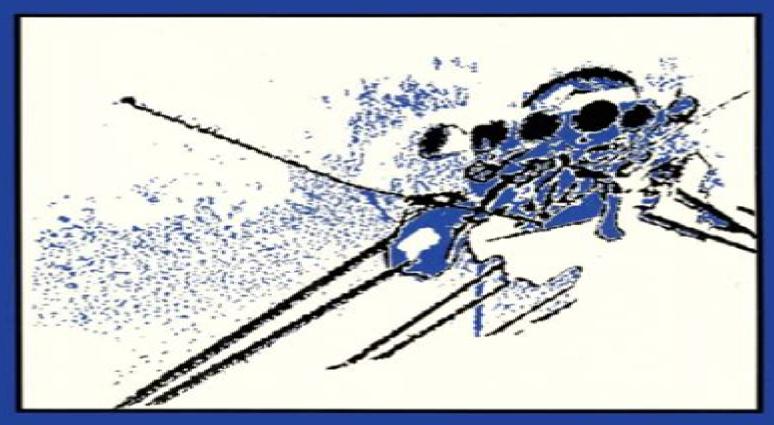
Designing Autonomous Agents

Theory and Practice from Biology to Engineering and Back

edited by Pattie Maes



Designing Autonomous Agents Theory Pra

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Designing Autonomous Agents Pattie Maes, 1990 Designing Autonomous Agents provides a summary and overview of the radically different architectures that have been developed over the past few years for organizing robots These architectures have led to major breakthroughs that promise to revolutionize the study of autonomous agents and perhaps artificial intelligence in general The new architectures emphasize more direct coupling of sensing to action distributedness and decentralization dynamic interaction with the environment and intrinsic mechanisms to cope with limited resources and incomplete knowledge The research discussed here encompasses such important ideas as emergent functionality task level decomposition and reasoning methods such as analogical representations and visual operations that make the task of perception more realistic Contents A Biological Perspective on Autonomous Agent Design Randall D Beer Hillel J Chiel Leon S Sterling Elephants Don t Play Chess Rodney A Brooks What Are Plans For Philip E Agre and David Chapman Action and Planning in Embedded Agents Leslie Pack Kaelbling and Stanley J Rosenschein Situated Agents Can Have Goals Pattie Maes Exploiting Analogical Representations Luc Steels Internalized Plans A Representation for Action Resources David W Payton Integrating Behavioral Perceptual and World Knowledge in Reactive Navigation Ronald C Arkin Symbol Grounding via a Hybrid Architecture in an Autonomous Assembly System Chris Malcolm and Tim Smithers Animal Behavior as a Paradigm for Developing Robot Autonomy Tracy L Anderson and Max Donath The 1993 Goddard Conference on Space Applications of Artificial Intelligence Carl F. Hostetter, 1993 **Proceedings of the Fifteenth Annual Conference of the Cognitive** Science Society Science Society Cognitive, Con, POLSON, 1993 This volume features the complete text of all regular papers posters and summaries of symposia presented at the 15th annual meeting of the Cognitive Science Society Christopher G. Langton, 1997 This book brings together a series of overview articles that appeared in the first three issues of the groundbreaking journal Artificial Life Virtual Interaction: Interaction in Virtual Inhabited 3D Worlds E. Granum, Lars Ovortrup, B. Holmgvist, S. Kolstrup, K. Halskov Madsen, 2013-03-09 Lars Ovortrup The world of interactive 3D multimedia is a cross institutional world Here researchers from media studies linguistics dramaturgy media technology 3D modelling robotics computer science sociology etc etc meet In order not to create a new tower of Babel it is important to develop a set of common concepts and references This is the aim of the first section of the book In Chapter 2 Jens F Jensen identifies the roots of interaction and interactivity in media studies literature studies and computer science and presents definitions of interaction as something going on among agents and agents and objects and of interactivity as a property of media supporting interaction Similarly he makes a classification of human users avatars autonomous agents and objects demon strating that no universal differences can be made We are dealing with a continuum While Jensen approaches these categories from a semiotic point of view in Chapter 3 Peer Mylov discusses similar issues from a psychological point of view Seen from the user's perspective a basic difference is that between stage and back stage or rather front stage i e between

the real I and we and the virtual representational I and we Focusing on the computer as a stage in Chapter 4 Kj0lner and Lehmann use the theatre metaphor to conceptualize the stage phenomena and the relationship between stage and front Advances in Artificial Life Federico Moran, 1995-05-24 This volume contains 71 revised refereed papers including seven invited surveys presented during the Third European Conference on Artificial Life ECAL 95 held in Granada Spain in June 1995 Originally AL was concerned with applying biologically inspired solutions to technology and with examining computational expertise in order to reproduce and understand life processes Despite its short history AL now is becoming a mature scientific field The volume reports the state of the art in this exciting area of research there are sections on foundations and epistemology origins of life and evolution adaptive and cognitive systems artificial worlds robotics and emulation of animal behavior societies and collective behavior biocomputing and applications and common tools MIT Encyclopedia of the Cognitive Sciences (MITECS) Robert A. Wilson, Frank C. Keil, 2001-09-04 Since the 1970s the cognitive sciences have offered multidisciplinary ways of understanding the mind and cognition The MIT Encyclopedia of the Cognitive Sciences MITECS is a landmark comprehensive reference work that represents the methodological and theoretical diversity of this changing field At the core of the encyclopedia are 471 concise entries from Acquisition and Adaptationism to Wundt and X bar Theory Each article written by a leading researcher in the field provides an accessible introduction to an important concept in the cognitive sciences as well as references or further readings Six extended essays which collectively serve as a roadmap to the articles provide overviews of each of six major areas of cognitive science Philosophy Psychology Neurosciences Computational Intelligence Linguistics and Language and Culture Cognition and Evolution For both students and researchers MITECS will be an indispensable guide to the current state of the cognitive sciences From Animals to **Animats 3** Dave Cliff, 1994 August 8 12 1994 Brighton England From Animals to Animats 3 brings together research intended to advance the fron tier of an exciting new approach to understanding intelligence. The contributors represent a broad range of interests from artificial intelligence and robotics to ethology and the neurosciences Unifying these approaches is the notion of animat an artificial animal either simulated by a computer or embodied in a robot which must survive and adapt in progressively more challenging environments The 58 contributions focus particularly on well defined models computer simulations and built robots in order to help characterize and compare various principles and architectures capable of inducing adaptive behavior in real or artificial animals Topics include Individual and collective behavior Neural correlates of behavior Perception and motor control Motivation and emotion Action selection and behavioral sequences Ontogeny learning and evolution Internal world models and cognitive processes Applied adaptive behavior Autonomous robots Heirarchical and parallel organizations Emergent structures and behaviors Problem solving and planning Goal directed behavior Neural networks and evolutionary computation Characterization of environments A Bradford Book Software Agents and Soft Computing: Towards Enhancing Machine Intelligence Hyacinth S. Nwana, 1997-01-22 This

carefully arranged book is mainly based on work done by the Intelligent Systems Research Group at BT Laboratories essentially in cooperation with internationally leading scientists from outside BT It opens with a detailed introduction surveying the area and putting the work presented in context Conceptual issues surrounding intelligent agents and multi agent systems are investigated and the practical and industrial applicability of this exciting new technology is demonstrated One section is devoted to the rationale philosophy and techniques of the emerging area of soft computing The final section outlines the broader context in dealing with machine intelligence in general and intelligent software systems in particular TELEMATICS AND INFORMATICS: AN INTERNATIONAL JOURNAL ON TELECOMMUNICATIONS & INFORMATION

Integrating Practice, Theory, and Design for Engineers P. K. Raju, 2001 TECHNOLOGY ,1992 **Anti-boxology** Phoebe Sengers, 1998 Abstract Artificial Intelligence AI the design of technology with attributes that we traditionally associate with living beings generally follows the broader scientific tradition of focusing on technical problems and their solutions within a relatively constrained framework The cultural studies of science on the other hand insists that scientific work should be understood as it springs from and influences other cultural phenomena including the background of metaphors and assumptions that influence the way scientists do their work In this thesis I explore the possibilities for AI and the cultural studies of science to engage in a mutually beneficial alliance by studying AI as a culturally situated activity and by using results of that study to generate novel technology Specifically I focus on the design of autonomous agents programs which are intended to represent a complete person animal or character In the alternative AI tradition these agents are created from a set of independent building blocks termed behaviors A major open question is how these behaviors can be synthesized to create an agent with overall coherent behavior I trace the problems in behavior integration to a strategy called atomization that AI shares with industrialization and psychiatric institutionalization Atomization is the process of breaking agents into modular chunks with limited interaction and represents a catch 22 for AI while this strategy is essential for building understandable code it is fatal for creating agents that have the overall coherence we have come to associate with living beings I tackle this problem of integration by redefining the notion of agent Instead of seeing agents as autonomous creatures with little reference to their sociocultural context I suggest that agents can be thought of in the style of cultural studies as a form of communication between the agent s designer and the audience which will try to comprehend the agent s activity With this metaphor as a basis it becomes clear that we need to integrate not the agent s internally defined code but the way in which the agent presents itself to the user Narrative psychology suggests that agents will be maximally comprehensible as intentional beings if they are structured to provide cues for narrative I therefore build an agent architecture the Expressivator which provides support for narratively comprehensible agents most notably by using behavioral transitions to link atomic behavoirs into narrative sequences A Neuro-computational Mobile Robot Architecture for Mapping Localization and Navigation Vassilios Morellas, 1995 **Intelligent Agents** ,1998 Intelligent

Autonomous Vehicles 1998 (IAV'98) Miguel Á. Salichs, Aarne Halme, 1998 These proceedings contain papers presented at the 3rd IFAC Symposium on Intelligent Autonomous Vehicles held in Madrid Spain The aim of the symposium was to present and discuss research and development on advanced applications in the field of land based marine and aerospace intelligent autonomous vehicles The papers describe not only new methods and technologies on solving classic problems related with intelligent autonomous vehicles but also new approaches to their design such as new architectures topological navigation and self learning systems

Proceedings of the IASTED International Conference M. H. Hamza, 1996

Advances in

Artificial Intelligence, 1996

From Animals to Animats:, 2004

Fourth Annual Symposium on Human Interaction with Complex Systems [HICS' 98] IEEE Computer Society, 1998 This text on the subject of computational intelligence includes coverage of dialog design for interactive systems aerospace systems dynamics of cognitive demands coordination and control in virtual workspaces performance and simulation of complex dynamic system and joint cognitive systems

Dynamic Systems and Control, 1995

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