



# Discrete Time Control Systems

**Yijin Wang**



## **Discrete Time Control Systems:**

*Discrete-time Control Systems* Katsuhiko Ogata, 1995 In depth discussions of selected topics such as Z transform and pole placement when the control signal was a vector quantity have been moved to optional Appendices discusses in detail the theoretical background for designing control systems offers a greatly expanded treatment of the pole placement design with minimum order observer by means of state space approach Ch 6 and polynomial equations approach Ch 7 features a new chapter on the polynomial equations approach to the control systems design as an alternative to the design of control systems via pole placement with minimum order observers Includes the design of model matching control systems emphasizes the usefulness of MATLAB for studying discrete time control systems showing how to use MATLAB optimally to obtain numerical solutions that involve various types of vector matrix operations plotting response curves and system design based on quadratic optimal control presents many instructive examples and worked out problems throughout the entire book

**Discrete-Time Control System Design with Applications** C.A. Rabbath, N. Léchevin, 2013-12-02 This unique book provides a bridge between digital control theory and vehicle guidance and control practice It presents practical techniques of digital redesign and direct discrete time design suitable for a real time implementation of controllers and guidance laws at multiple rates and with and computational techniques The theory of digital control is given as theorems lemmas and propositions The design of the digital guidance and control systems is illustrated by means of step by step procedures algorithms and case studies The systems proposed are applied to realistic models of unmanned systems and missiles and digital implementation Discrete-time and Computer Control Systems James A. Cadzow, Hinrich R. Martens, 1970 Treats systems in which the digital computer plays a central role Discrete Time Control Systems, 2/e Katsuhiko Ogata, 1995

**Discrete-time Control Systems** Katsuhiko Ogata, 1987 *Discrete-time Control Systems* Katsuhiko Ogata, 2006 Discrete-time Control Systems Katsuhiko Ogata, 1987 Schaum's Outline of Feedback and Control Systems, Second Edition Joseph J. DiStefano, Allen Stubberud, Ivan J. Williams, 1990 If you want top grades and thorough understanding of feedback and control systems both analog and digital in less study time this powerful study tool is the best tutor you can have It takes you step by step through the subject and gives you accompanying problems with fully worked solutions plus hundreds of additional problems with answers at the end of chapters so you can measure your progress You also get the benefit of clear detailed illustrations Famous for their clarity wealth of illustrations and examples and lack of tedious detail Schaum's Outlines have sold more than 30 million copies worldwide This guide will show you why **Hydraulic Control Systems** Noah D. Manring, Roger C. Fales, 2019-08-14 Provides key updates to a must have text on hydraulic control systems This fully updated second edition offers students and professionals a reliable and comprehensive guide to the hows and whys of today's hydraulic control system fundamentals Complete with insightful industry examples it features the latest coverage of modeling and control systems with a widely accepted approach to systems design The book also offers all new information

on advanced control topics auxiliary components reservoirs accumulators coolers filters hybrid transmissions multi circuit systems and digital hydraulics Chapters in Hydraulic Control Systems 2nd Edition cover fluid properties fluid mechanics dynamic systems and control hydraulic valves pumps and actuators auxiliary components and both valve and pump controlled hydraulic systems The book presents illustrative case studies throughout that highlight important topics and demonstrate how equations can be implemented and used in the real world It also features end of chapter exercises to help facilitate learning It is a powerful tool for developing a solid understanding of hydraulic control systems that will serve all practicing engineers in the field Provides a useful review of fluid mechanics and system dynamics Offers thorough analysis of transient fluid flow forces within valves Adds all new information on advanced control topics auxiliary components hybrid transmissions multi circuit systems and digital hydraulics Discusses flow ripple for both gear pumps and axial piston pumps Presents updated analysis of the pump control problems associated with swash plate type machines Showcases a successful methodology for hydraulic system design Features reduced order models and PID controllers showing control objectives of position velocity and effort Hydraulic Control Systems 2nd Edition is an important book for undergraduate and first year graduate students taking courses in fluid power It is also an excellent resource for practicing engineers in the field of fluid power

*Discrete-Time Control Systems 2Nd Ed.* Katsuhiko Ogata, 2012      *CONTROL SYSTEMS, ROBOTICS AND AUTOMATION - Volume II* Heinz Unbehauen, 2009-10-11 This Encyclopedia of Control Systems Robotics and Automation is a component of the global Encyclopedia of Life Support Systems EOLSS which is an integrated compendium of twenty one Encyclopedias This 22 volume set contains 240 chapters each of size 5000 30000 words with perspectives applications and extensive illustrations It is the only publication of its kind carrying state of the art knowledge in the fields of Control Systems Robotics and Automation and is aimed by virtue of the several applications at the following five major target audiences University and College Students Educators Professional Practitioners Research Personnel and Policy Analysts Managers and Decision Makers and NGOs      **Discrete-data Control Systems** Benjamin C. Kuo, 1970 Sampling and data reconstruction processes The Z transform The state variable technique Stability of discrete data systems Time optimal control of discrete time systems Optimal design of discrete data systems by performance index Statistical design wiener filter Statistical design kalman filter Digital simulation Problems      [Linear Systems: Analysis and Applications , Second Edition](#) ,

**Fundamentals of Control Engineering** Aniruddh Mohan, 2025-02-20 Fundamentals of Control Engineering explores the evolving landscape of control engineering covering classical principles and advanced methodologies Authored by experts this book provides a comprehensive understanding of control systems principles applications and challenges It adopts a multifaceted approach covering classical control theory modern strategies and specialized topics like quantum control intelligent systems and biomedical control Each chapter balances theoretical principles with practical applications making it suitable for students researchers and engineers The inclusion of advanced topics such as quantum control and intelligent

systems reflects emerging technologies reshaping the field Practical examples and case studies showcase control engineering s relevance in various industries while interdisciplinary perspectives emphasize integrating control principles with fields like AI quantum mechanics and healthcare The book also addresses ethical considerations reliability issues and quantum coherence providing a holistic view of the field s opportunities and hurdles Fundamentals of Control Engineering is a valuable resource for understanding the multidisciplinary facets of control systems ideal for students researchers and professionals

*Schaum's Outline of Feedback and Control Systems, 3rd Edition* Joseph J. Distefano, 2013-11-08 Tough Test Questions Missed Lectures Not Enough Time Fortunately for you there s Schaum s This all in one package includes more than 700 fully solved problems examples and practice exercises to sharpen your problem solving skills Plus you will have access to 20 detailed videos featuring instructors who explain the most commonly tested problems it s just like having your own virtual tutor You ll find everything you need to build confidence skills and knowledge for the highest score possible More than 40 million students have trusted Schaum s to help them succeed in the classroom and on exams Schaum s is the key to faster learning and higher grades in every subject Each Outline presents all the essential course information in an easy to follow topic by topic format You also get hundreds of examples solved problems and practice exercises to test your skills This Schaum s Outline gives you 700 fully solved problems Extra practice on topics such as differential equations and linear systems transfer functions block diagram algebra and more Support for all major textbooks for feedback and control systems courses Fully compatible with your classroom text Schaum s highlights all the important facts you need to know Use Schaum s to shorten your study time and get your best test scores Schaum s Outlines Problem Solved

Digital Control Engineering M. Gopal, 1988

**Discrete-time Control Problems Using MATLAB and the Control System Toolbox** Joe H. Chow, Dean K. Frederick, Nicholas W. Chbat, 2003 Using the power of MATLAB and its Control System Toolbox this book is the ideal supplement for a digital control systems course Students are able to use a digital computer to rapidly work a wide range of numerical problems and gain deeper insight in control design The book is built around illustrative examples that demonstrate the steps involved in the analysis and design process The examples are followed by a variety of problems that span the spectrum from follow up what if problems to simple textbook type reinforcement problems to open ended exploratory problems and to realistic comprehensive problems This book is part of the Bookware Companion Series

**Discrete Time Control Systems** Katsuhiko Ogata, 1995

**Imprecise Computation in Real-time Control Systems** Changwen Liu, University of Illinois at Urbana-Champaign. Department of Computer Science, 1995 Abstract The thesis is concerned with the behavior of corrupted real time control systems and their corrupted trajectories The difference between the corrupted trajectory and the precise trajectory is called the tracking error We analyze the consequence of imprecise computation caused by corrupted input and or prematurely terminated output computation on tracking errors for single input single output and multiple input multiple output time invariant systems with deterministic errors as well as random

errors We establish the tracking error models and give upper bounds of the tracking errors We find conditions under which the imprecise computation has certain desired convergence properties and show how to design control systems so that the systems have satisfactory performance

### **Nonlinear Discrete-Time Design Methods for Missile Flight Control**

**Systems**, 2004 Design methods for discrete time linear control systems have reached an advanced level of maturity However the direct design of nonlinear discrete time control systems remains to be fully developed Although textbooks are available on nonlinear control system design literature on discrete time nonlinear control system design is rather sparse From an applications point of view discrete time designs are important because most controllers are implemented using digital computers Design techniques of interest in this paper are those that permit the synthesis of discrete time controllers for continuous time nonlinear dynamic systems The present work is motivated by the need to implement nonlinear control system designs synthesized using computer aided design techniques<sup>6 7</sup> onboard missiles Three different discrete time control system design techniques have been investigated in the present research All of them are discrete time analogs of continuous time nonlinear system design techniques discussed in the literature The first approach is the discrete time version of the state dependent Riccati equation SDRE technique discussed in References 8 and 9 The second design technique is a discrete time version of the recursive backstepping<sup>10</sup> methodology and employs discretized system dynamics The third technique is the discrete time version of the feedback linearization design approach In this last technique the system dynamics is first transformed into a linear time invariant form through the definition of state variable feedback The transformed model is then converted into discrete time form by defining sample holds at the input and the outputs The discretized is linear model is then used for control system design All three techniques have been employed for the design of missile flight control systems Section II will present each of the design techniques in detail

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