CONTROL THEORY FOR PARTIAL DIFFERENTIAL EQUATIONS: CONTINUOUS AND APPROXIMATION THEORIES

I

ABSTRACT PARABOLIC SYSTEMS

IRENA LASIECKA
ROBERTO TRIGGIANI

Control Theory For Partial Differential Equations Vol 1 Continuous And Approximation Theories

Robert A. Meyers

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    Control Theory for Partial Differential Equations: Volume 1, Abstract Parabolic Systems Irena Lasiecka,Roberto Triggiani,2000-02-13 Originally published in 2000 this is the first volume of a comprehensive two volume treatment of quadratic optimal control theory for partial differential equations over a finite or infinite time horizon and related differential integral and algebraic Riccati equations Both continuous theory and numerical approximation theory are included The authors use an abstract space operator theoretic approach which is based on semigroups methods and which is unifying across a few basic classes of evolution The various abstract frameworks are motivated by and ultimately directed to partial differential equations with boundary point control Volume 1 includes the abstract parabolic theory for the finite and infinite cases and corresponding PDE illustrations as well as various abstract hyperbolic settings in the finite case It presents numerous fascinating results These volumes will appeal to graduate students and researchers in pure and applied mathematics and theoretical engineering with an interest in optimal control problems   **Control Theory for Partial Differential Equations** Irena Lasiecka,Roberto Triggiani,2013-08-13 First of a two volume treatise on deterministic control systems modeled by multi dimensional partial differential equations originally published in 2000   Control Theory for Partial Differential Equations: Volume 2, Abstract Hyperbolic-like Systems Over a Finite Time Horizon Irena Lasiecka,Roberto Triggiani,2000-02-13 Originally published in 2000 this is the second volume of a comprehensive two volume treatment of quadratic optimal control theory for partial differential equations over a finite or infinite time horizon and related differential integral and algebraic Riccati equations Both continuous theory and numerical approximation theory are included The authors use an abstract space operator theoretic approach which is based on semigroups methods and which unifies across a few basic classes of evolution The various abstract frameworks are motivated by and ultimately directed to partial differential equations with boundary point control Volume 2 is focused on the optimal control problem over a finite time interval for hyperbolic dynamical systems A few abstract models are considered each motivated by a particular canonical hyperbolic dynamics It presents numerous fascinating results These volumes will appeal to graduate students and researchers in pure and applied mathematics and theoretical engineering with an interest in optimal control problems
    Controllability of Partial Differential Equations Governed by Multiplicative Controls Alexander Y. Khapalov,2010-05-19 This monograph addresses the global controllability of partial differential equations in the context of multiplicative or bilinear controls which enter the model equations as coefficients The methodology is illustrated with a variety of model equations
    Elementary Feedback Stabilization of the Linear Reaction-Convection-Diffusion Equation and the Wave Equation Weijiu Liu,2009-12-01 Unlike abstract approaches to advanced control theory this volume presents key concepts through concrete examples Once the basic fundamentals are established readers can apply them to solve other control problems of partial differential equations   **Robust Engineering Designs of Partial Differential Systems and Their**

Applications Bor-Sen Chen,2021-12-22 Most systems in science engineering and biology are of partial differential systems PDSs modeled by partial differential equations Many books about partial differential equations have been written by mathematicians and mainly address some fundamental mathematic backgrounds and discuss some mathematic properties of partial differential equations Only a few books on PDSs have been written by engineers however these books have focused mainly on the theoretical stabilization analysis of PDSs especially mechanical systems This book investigates both robust stabilization control design and robust filter design and reference tracking control design in mechanical signal processing and control systems to fill a gap in the study of PDSs Robust Engineering Designs of Partial Differential Systems and Their Applications offers some fundamental background in the first two chapters The rest of the chapters focus on a specific design topic with a corresponding deep investigation into robust H filtering stabilization or tracking design for more complex and practical PDSs under stochastic fluctuation and external disturbance This book is aimed at engineers and scientists and addresses the gap between the theoretical stabilization results of PDSs in academic and practical engineering designs more focused on the robust H filtering stabilization and tracking control problems of linear and nonlinear PDSs under intrinsic random fluctuation and external disturbance in industrial applications Part I provides backgrounds on PDSs such as Galerkin s and finite difference methods to approximate PDSs and a fuzzy method to approximate nonlinear PDSs Part II examines robust H filter designs for the robust state estimation of linear and nonlinear stochastic PDSs And Part III treats robust H stabilization and tracking control designs of linear and nonlinear PDSs Every chapter focuses on an engineering design topic with both theoretical design analysis and practical design examples   *The Control Handbook (three volume set)* William S. Levine,2018-10-08 At publication The Control Handbook immediately became the definitive resource that engineers working with modern control systems required Among its many accolades that first edition was cited by the AAP as the Best Engineering Handbook of 1996 Now 15 years later William Levine has once again compiled the most comprehensive and authoritative resource on control engineering He has fully reorganized the text to reflect the technical advances achieved since the last edition and has expanded its contents to include the multidisciplinary perspective that is making control engineering a critical component in so many fields Now expanded from one to three volumes The Control Handbook Second Edition brilliantly organizes cutting edge contributions from more than 200 leading experts representing every corner of the globe They cover everything from basic closed loop systems to multi agent adaptive systems and from the control of electric motors to the control of complex networks Progressively organized the three volume set includes Control System Fundamentals Control System Applications Control System Advanced Methods Any practicing engineer student or researcher working in fields as diverse as electronics aeronautics or biomedicine will find this handbook to be a time saving resource filled with invaluable formulas models methods and innovative thinking In fact any physicist biologist mathematician or researcher in any number of fields developing or improving products and systems will find the answers and ideas they need

As with the first edition the new edition not only stands as a record of accomplishment in control engineering but provides researchers with the means to make further advances **Control Theory for Partial Differential Equations** Irena Lasiecka,2000 **Mathematics of Complexity and Dynamical Systems** Robert A. Meyers,2011-10-05 Mathematics of Complexity and Dynamical Systems is an authoritative reference to the basic tools and concepts of complexity systems theory and dynamical systems from the perspective of pure and applied mathematics Complex systems are systems that comprise many interacting parts with the ability to generate a new quality of collective behavior through self organization e g the spontaneous formation of temporal spatial or functional structures These systems are often characterized by extreme sensitivity to initial conditions as well as emergent behavior that are not readily predictable or even completely deterministic The more than 100 entries in this wide ranging single source work provide a comprehensive explication of the theory and applications of mathematical complexity covering ergodic theory fractals and multifractals dynamical systems perturbation theory solitons systems and control theory and related topics Mathematics of Complexity and Dynamical Systems is an essential reference for all those interested in mathematical complexity from undergraduate and graduate students up through professional researchers **Introduction to Infinite-Dimensional Systems Theory** Ruth Curtain,Hans Zwart,2020-04-05 Infinite dimensional systems is a well established area of research with an ever increasing number of applications Given this trend there is a need for an introductory text treating system and control theory for this class of systems in detail This textbook is suitable for courses focusing on the various aspects of infinite dimensional state space theory This book is made accessible for mathematicians and post graduate engineers with a minimal background in infinite dimensional system theory To this end all the system theoretic concepts introduced throughout the text are illustrated by the same types of examples namely diffusion equations wave and beam equations delay equations and the new class of platoon type systems Other commonly met distributed and delay systems can be found in the exercise sections Every chapter ends with such a section containing about 30 exercises testing the theoretical concepts as well An extensive account of the mathematical background assumed is contained in the appendix *Control Theory for Partial Differential Equations: Volume 2, Abstract Hyperbolic-Like Systems Over a Finite Time Horizon* Irena Lasiecka,Roberto Triggiani,2014-02-20 Second of a two volume treatise on deterministic control systems modeled by multi dimensional partial differential equations **Proceedings of the ... American Control Conference** ,2005 *Mathematical Reviews* ,2004 **Discrete and Continuous Dynamical Systems** ,2008 **SIAM Journal on Control and Optimization** Society for Industrial and Applied Mathematics,2009 Advances in Differential Equations ,1998 *Introduction to the Mathematical Theory of Control* Alberto Bressan,Benedetto Piccoli,2007 **Dynamics of Continuous, Discrete & Impulsive Systems** ,2004 **Boletim da Sociedade Paranaense de Matemática** ,2004 **Feedback Control for Aerodynamics** R. Chris Camphouse,Seddik M. Djouadi,James H. Myatt,2006 The two dimensional Burgers equation is used as a surrogate for the

governing equations to test order reduction and control design approaches This scalar equation is selected because it has a nonlinearity that is similar to the Navier Stokes equation but it can be accurately simulated using far fewer states However the number of states required is still well above that for which a controller can be designed directly Two approaches for order reduction are used In both approaches proper orthogonal decomposition POD also known as Karhunen Loeve decomposition or principal component analysis is used with Galerkin projection In the first method the traditional POD approach of selecting the modes to be retained in the reduced order model is based on the energy content of the modes In the second method balanced truncation is used to select the appropriate modes Both approaches capture the dynamics of the input output system and are used for control design

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