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INTRODUCTION TO CONTROL OF OSCILLATIONS AND CHAOS

Alexander L. Fradkov & Alexander Yu. Pogromsky



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preservation of nature and the energy provision Suggests new approaches to development of various energy sources on the planet Includes the results of theoretical and experimental studies on the development of the geomechanical approaches for hydrocarbon production Contains the results of recent research in the field of interactions of the lithosphere atmosphere and hydrosphere of various scales energy exchange of the atmosphere and the ocean including changes under anthropogenic influences Proposes new physical and mathematical models of processes occurring in the environment both natural and anthropogenic as well as elaboration of existing ones This collected research is a valuable resource for specialists working in the oil gas and engineering industry to improve their understandings of the field Processes in GeoMedia—Volume VIII Tatiana Chaplina, 2024-10-03 This book includes new results of theoretical and experimental studies of various scales of the processes occurring on the earth including the lithosphere atmosphere and hydrosphere Intensive development of research in these areas is due to several factors 1 the widespread introduction of computer technology allowing the calculation of complex phenomena 2 the invention and improvement of a new generation of geophysical instruments such as remote observation systems based on ships aircraft and satellites providing a large amount of data to objectively reflect a broad picture of the processes 3 the development of measurement techniques creating opportunities for controllable and reproducible laboratory data acquisition for generation of new ideas and concepts Their recent developments have facilitated our research and understanding of these academic fields The book enriches the understanding of the geophysical processes taking place in various environments lithosphere hydrosphere atmosphere including the anthropogenic one and it further contributes to their development This collected research is a valuable resource for specialists working in the oil gas and engineering industry to improve their understandings of the field **Select Topics of Econophysics** Amit Sinha, 2024-11-04 Economics requires understanding and analyzing forces that bring buyers and sellers to a market place who then negotiate exchanges of goods and services based on a mutually agreeable price Economists have their own method of modeling whereby models are first conceived of some notion of economic and financial thinking before being empirically tested and anomalies are then recognized if the observed data is inconsistent with the hypothetical underpinning This is in inherent contradiction with the modeling approaches of physicists who develop their theories principle and laws after observing empirical data The awareness that physics can enlighten the understanding of human behavior and thus economics and the interest of physicists in applying their training and models to understanding the complexities of finance and economics led to the creation of a new field of study appropriately termed as Econophysics Selected Topics on Econophysics is a collection of essays on topics that enhance and enrich our understanding of economic modeling when the same rigor of modelling used by physicists is brought to developing financial and economic theories These articles include discussions on modeling bitcoins stock index modeling using geometric Brownian motion agent based modeling wealth distribution modeling as well as modeling related to fractal regression and chaotic processes. This interdisciplinary book will interest

researchers graduate students and professionals in the fields of economics finance as well as physics Applied Mechanics Reviews ,2001 CONTROL SYSTEMS, ROBOTICS AND AUTOMATION - Volume XIII Heinz D. Unbehauen, 2009-10-11 This Encyclopedia of Control Systems Robotics and Automation is a component of the global Encyclopedia of Life Support Systems EOLSS which is an integrated compendium of twenty one Encyclopedias This 22 volume set contains 240 chapters each of size 5000 30000 words with perspectives applications and extensive illustrations It is the only publication of its kind carrying state of the art knowledge in the fields of Control Systems Robotics and Automation and is aimed by virtue of the several applications at the following five major target audiences University and College Students Educators Professional Practitioners Research Personnel and Policy Analysts Managers and Decision Makers and NGOs Proceedings of the ... ASME Design Engineering Technical Conferences ,2003 Proceedings ,2000 **Publications in Engineering Index of Conference Proceedings** British Library. Document Supply Centre, 2001 American Book Publishing .2002 Record ,2001 Control of Oscillations and Chaos Feliks Leonidovich Chernous'ko, Aleksandr L'vovich Fradkov, 2000 Trends in Industrial and Applied Mathematics Abul Hasan Siddiqi, M. Mathematical Reviews ,2004 Kocvara, 2002-08-31 This book contains current results of research on numerical solutions of Schrodinger type problems sampling theorems numerical methods for large scale non convex quadratic programming derivative free algorithms free material optimization Moreau s sweeping process and a perspective on industrial mathematics work in recent years The book also includes wavelet based digital watermarking techniques and computer simulation of meteorological parameters One chapter of the book is also devoted to the importance of strange attractors for industrial mathematics Audience Academic researchers as well as researchers working in industry **Chaos, Solitons and Fractals** ,2002 Neural Computation Biped Robots Armando Carlos De Pina Filho, 2011-02-04 Biped robots represent a very interesting research ,2003 subject with several particularities and scope topics such as mechanical design gait simulation patterns generation kinematics dynamics equilibrium stability kinds of control adaptability biomechanics cybernetics and rehabilitation technologies We have diverse problems related to these topics making the study of biped robots a very complex subject and many times the results of researches are not totally satisfactory However with scientific and technological advances based on theoretical and experimental works many researchers have collaborated in the evolution of the biped robots design looking for to develop autonomous systems as well as to help in rehabilitation technologies of human beings Thus this book intends to present some works related to the study of biped robots developed by researchers worldwide

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